

Hidden Markov Modeling



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Quantitative Understanding in Biology
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Markov Modeling

- Stochastic process
- State machine assumption
- Transitions probabilistic
- Markov assumption
 - Current state depends only on a finite history of previous states
 - 1st order: current state depends only on previous state $\rightarrow P(X_t | X_{0:t-1}) = P(X_t | X_{t-1})$

Markov Process

- To define 1st order process need
 - States
 - sunny, cloudy, rainy
 - Initial probabilities (π vector)
 - [sunny cloudy rainy] = [0.8 0.1 0.1]
 - Transition probabilities (A matrix)

| | | | | | |
|------------------|-------|------|--------------|-------|------|
| | | | <i>Today</i> | | |
| | | | sun | cloud | rain |
| <i>Yesterday</i> | sun | 0.50 | 0.375 | 0.125 | |
| | cloud | 0.25 | 0.125 | 0.625 | |
| | rain | 0.25 | 0.375 | 0.375 | |

What is a HMM?

- Markov process with unobserved states
- Do observe output dependent on state
 - Hermit forecast weather
- HMM definition
 - Initial probabilities (π vector)
 - Transition probabilities (A matrix)
 - Emission probabilities (B matrix)

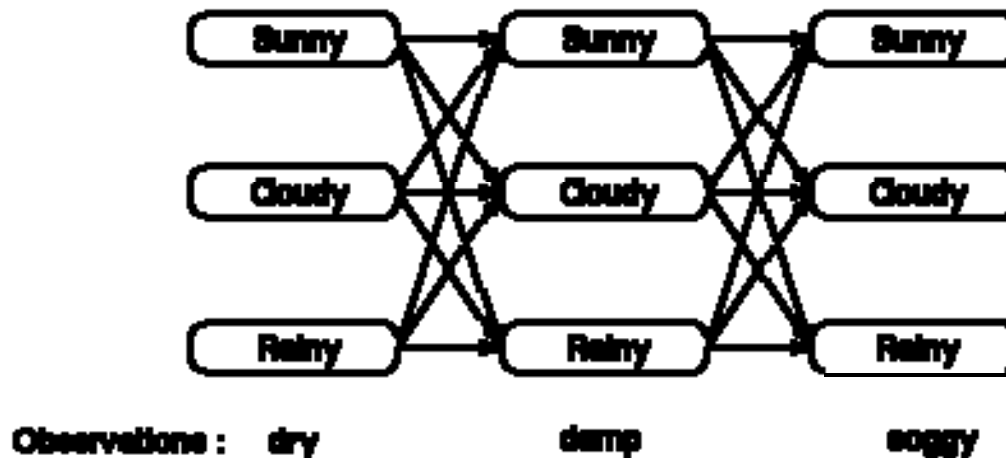
| | | Seaweed | | | |
|----------------|--------------|----------------|---------------|-------------|--------------|
| | | Dry | Dryish | Damp | Soggy |
| weather | Sun | 0.60 | 0.20 | 0.15 | 0.05 |
| | Cloud | 0.85 | 0.25 | 0.85 | 0.85 |
| | Rain | 0.05 | 0.10 | 0.35 | 0.50 |

HMM Uses

- Evaluation
 - Match most likely system to observations
 - Forward algorithm
- **Decoding**
 - Find most probable sequence of hidden states
 - Viterbi algorithm
- Learning
 - Define HMM parameters to a given data set
 - Forward-backward algorithm

Evaluation

- Probability of observed sequence given HMM
- Number of paths needed increases exponentially with time
- Solution: Use time invariance of probabilities



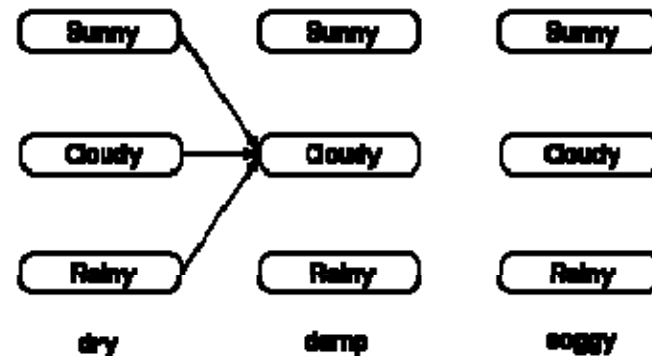
Forward Algorithm

- Reduce complexity with recursion
 - N^T vs N^2T
- Partial probability α = sum of all possible paths to a state
 - $\alpha_{t+1}(j) = \Pr(\text{observation} \mid \text{hidden state is } j) \times \Pr(\text{all paths to state } j \text{ at time } t)$

$$\alpha_{t+1}(j) = b_{jk_{t+1}} \sum_{i=1}^n \alpha_t(i) a_{ij}$$

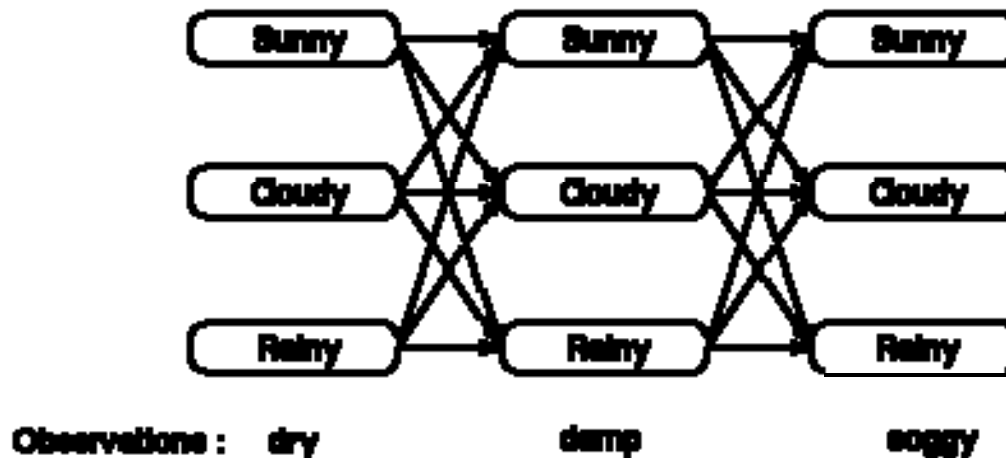
- Special case: $t = 1$

$$\alpha_1(j) = \pi(j) \cdot b_{jk_1}$$



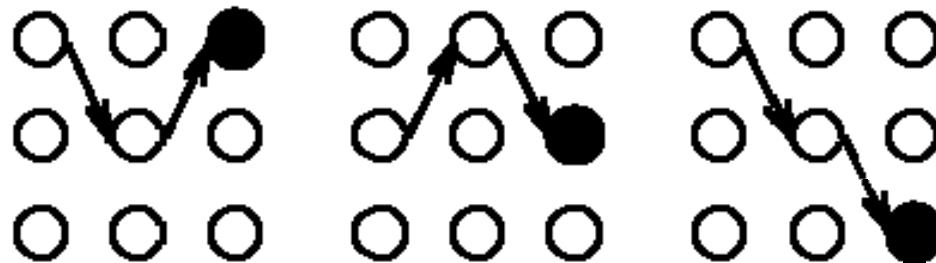
Decoding

- Find most probable sequence of hidden states
 - Maximize $\Pr(\text{observed sequence} \mid \text{hidden state combination})$
 - Again, reduce complexity with recursion!



Viterbi Algorithm

- Partial probability δ = most likely path to a state
- Overall best path = state with the max δ and its partial best path



Partial best paths, each with a δ

Viterbi Algorithm

- Probability of most probable path to state X

- $\Pr(X \text{ at time } t) = \max_{i=A,B,C} \Pr(i_{t-1}) \times \Pr(X | i) \times \Pr(\text{obs. at time } t | X)$

$$\delta_t(i) = \max_j (\delta_{t-1}(j) a_{ji} b_{ik_t})$$

- Special case: $t = 1$

$$\delta_1(i) = \pi(i) b_{ik_1}$$

- If I am here, by what route is it most likely I arrived?

- “Remember” past best states with backpointers

$$\phi_t(i) = \operatorname{argmax}_j (\delta_{t-1}(j) a_{ji})$$

Viterbi Algorithm

- Termination: determine state at final t

$$\mathbf{i}_t = \mathit{argmax}(\delta_T(\mathbf{i}))$$

- Back-track

– For t = t-1 \rightarrow 1

$$\mathbf{i}_t = \phi_{t+1}(\mathbf{i}_{t+1})$$

- Advantages

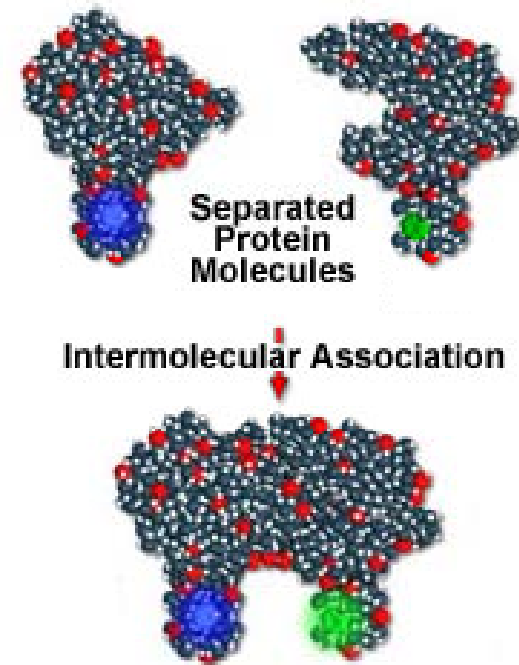
– Reduce complexity (N^T vs N^2T)

– Robust to noise

- Looks at whole sequence before deciding on most likely final state \rightarrow back-track to best path

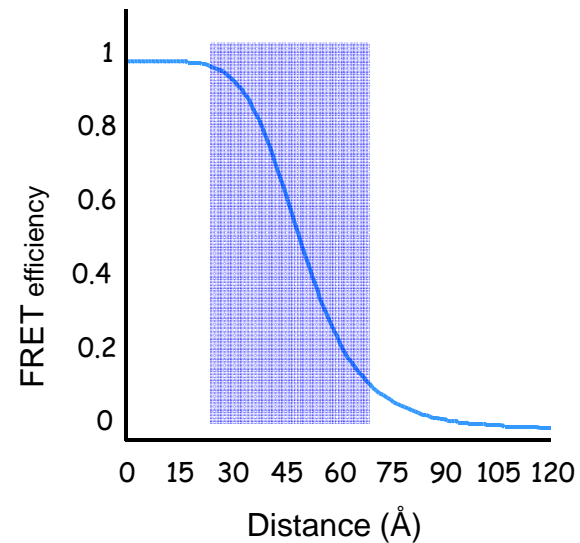
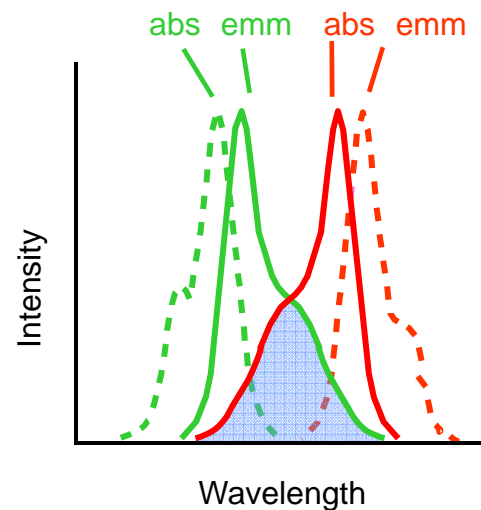
HMM Applications

- Single-molecule imaging
 - Molecular movements diffraction-limited (hidden)
 - Infer conformational changes from observed changes in fluorescence

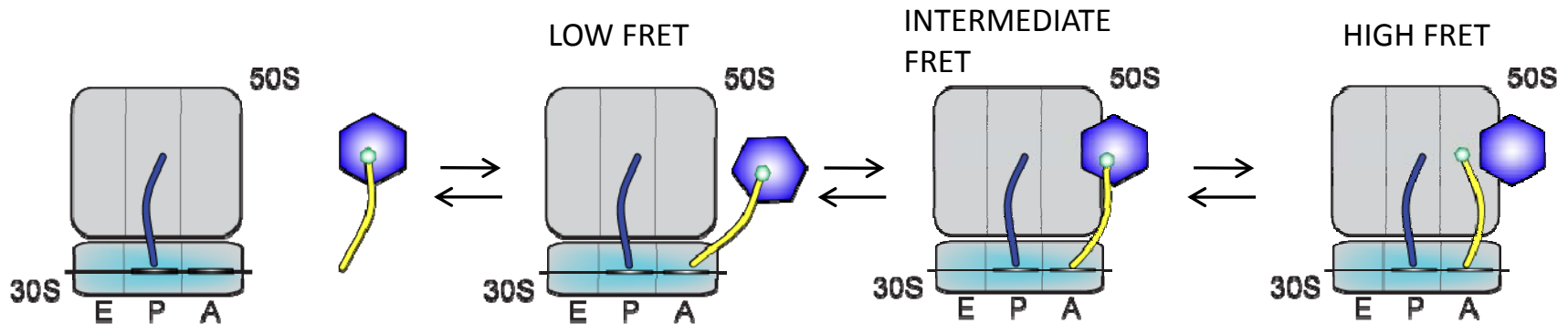
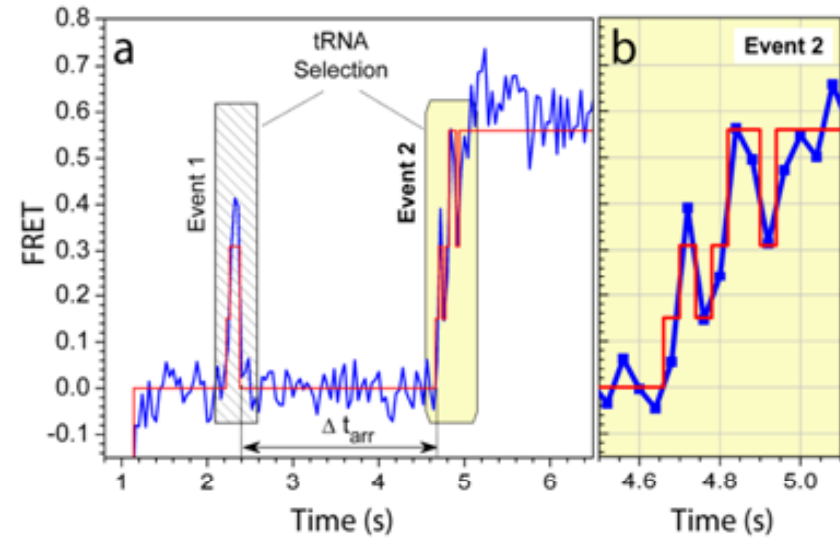
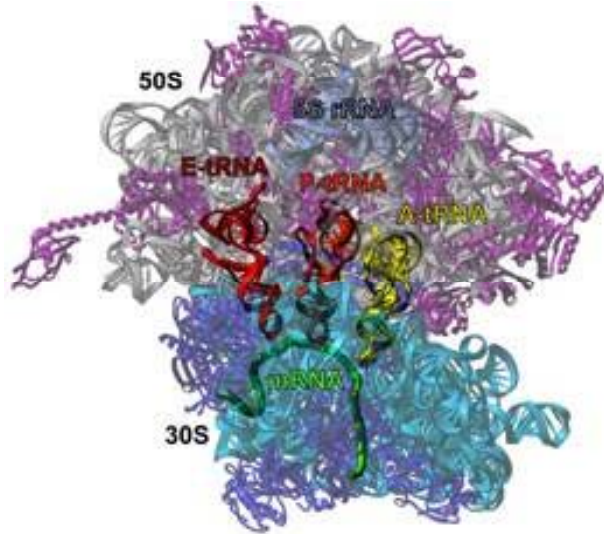


FRET

- Fluorescence Resonance Energy Transfer
- Used as a spectroscopic ruler
 - Measure real-time changes in molecular conformations

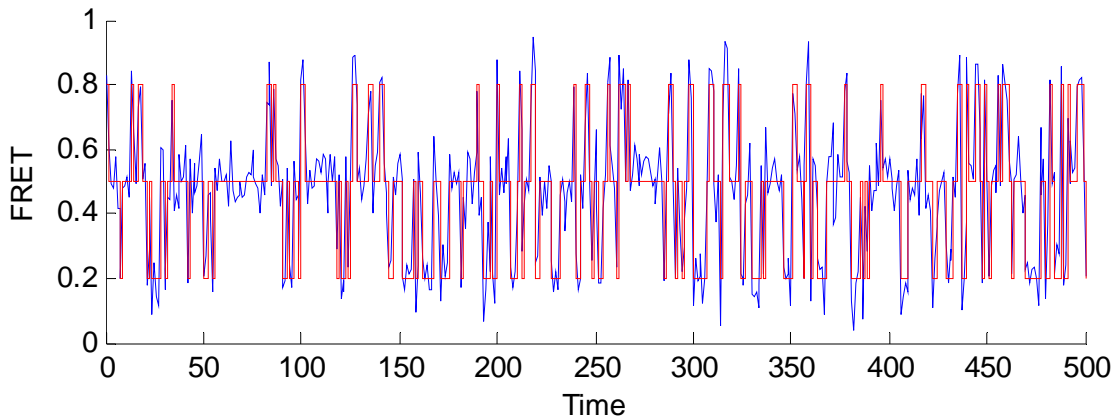
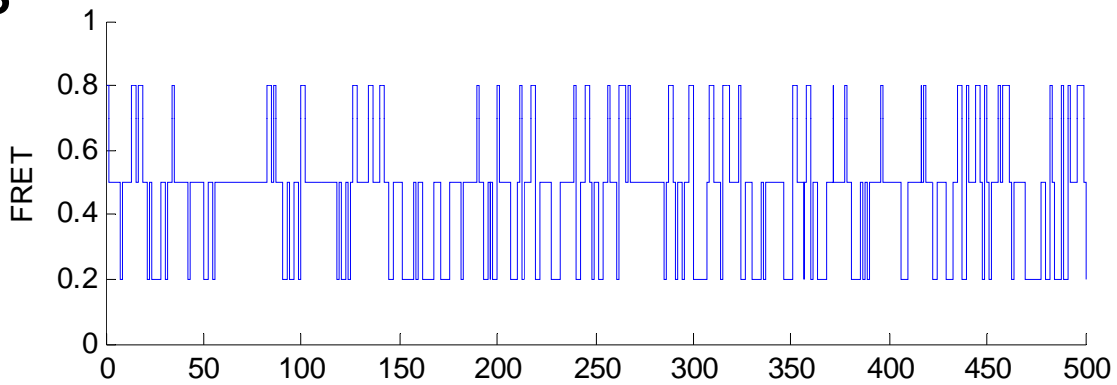


FRET Example - Ribosome



Simulation

- See how well model captures underlying states



Summary

- HMMs are useful to infer underlying Markov states of a system
- Many applications (speech to science)
- Advantage: computationally friendly
- Disadvantage: assumes time invariance in parameters

Additional Questions?